

Automated Testing of Cyber-Physical Systems

Shiva Nejati

SnT Centre/University of Luxembourg

Huawei Workshop

December 15, 2017

Acknowledgements

- **Lionel Briand**
- **Raja Ben Abdessalem**
- **Reza Matinnejad**
- **Industry partners: IEE, SES and Delphi**

Raja



Lionel



Reza



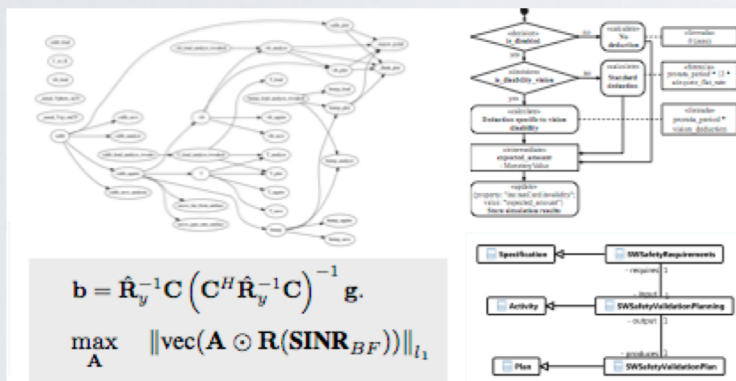
Cyber Physical Systems



Model-Based Development

CPS Model-Based Development

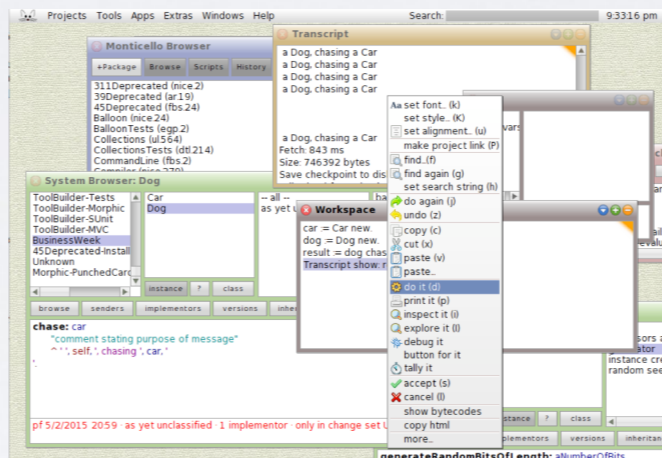
Model in the Loop MiL



Function modeling
(Matlab/Simulink)

- Controller
- Plant/Environment

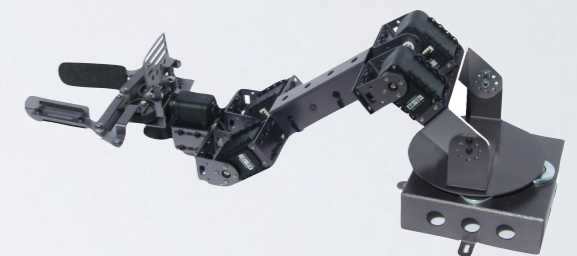
Software in the Loop SiL



Architecture modeling
(C-Code/SysML)

- Real-time analysis
- Integration

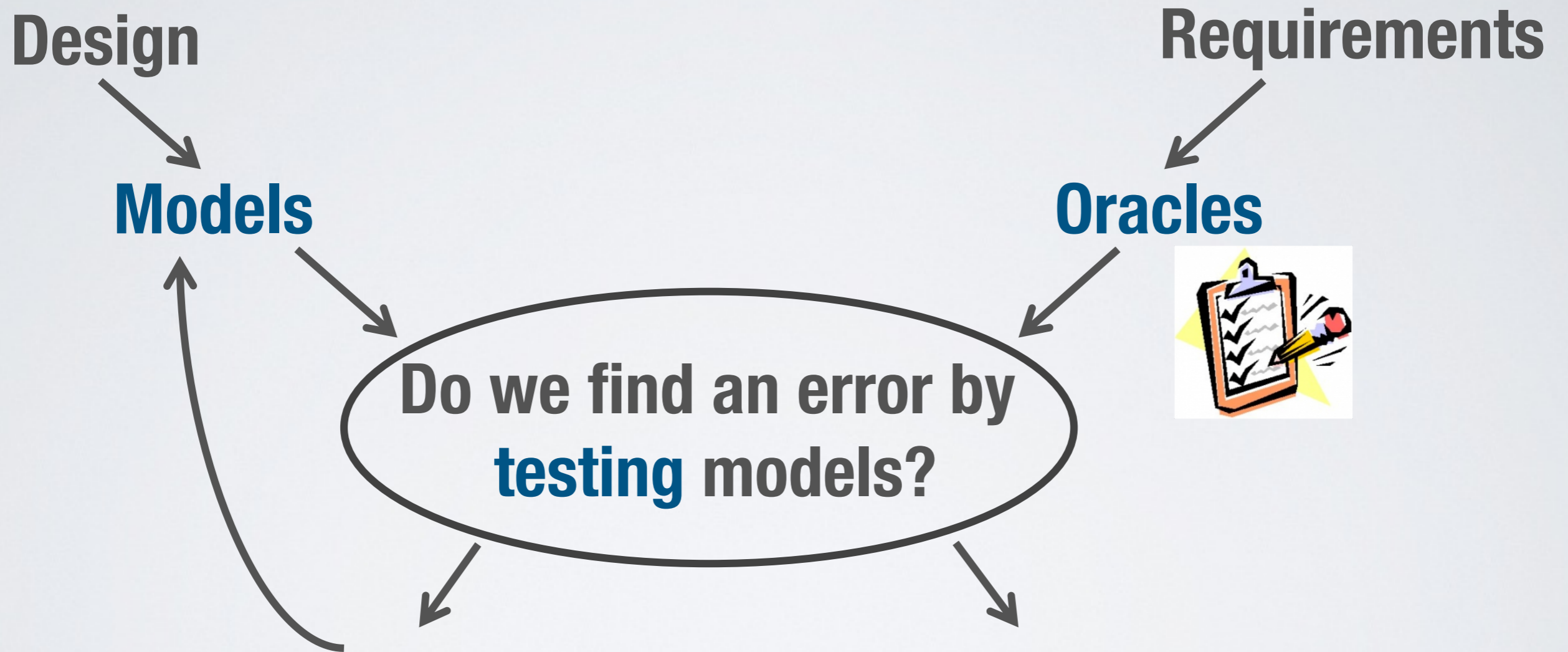
Hardware in the Loop HiL



Deployment
(embedded-C)

- Testing (Expensive)

Model Testing



Fundamental Questions

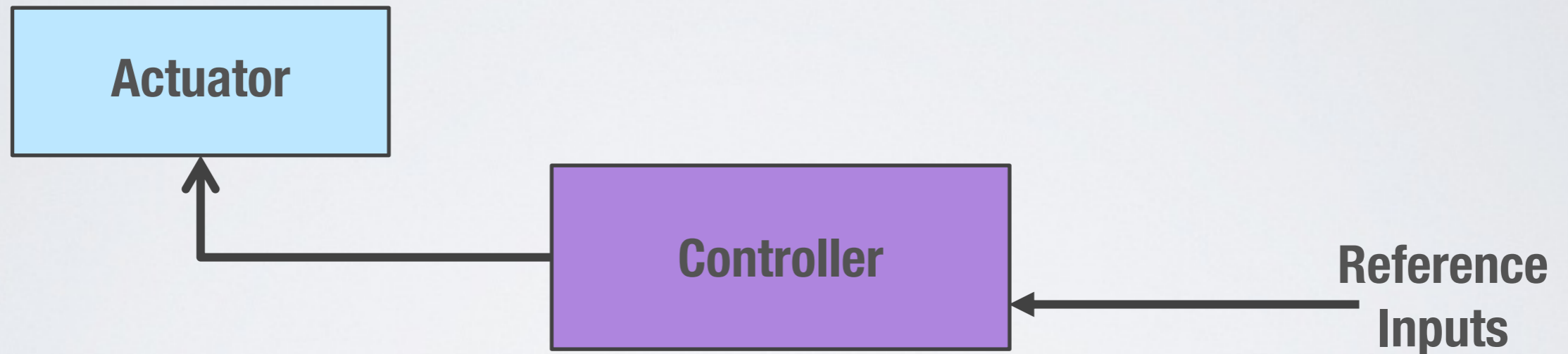
- What are the **useful and realistic models** of CPSs?
- How to **specify test oracles** to enable **effective testing of system requirements and design**?
- How to **design scalable testing techniques**?
 - Test case generation
 - Test case selection
 - Fault localization

**ARTIFICIAL
INTELLIGENCE**

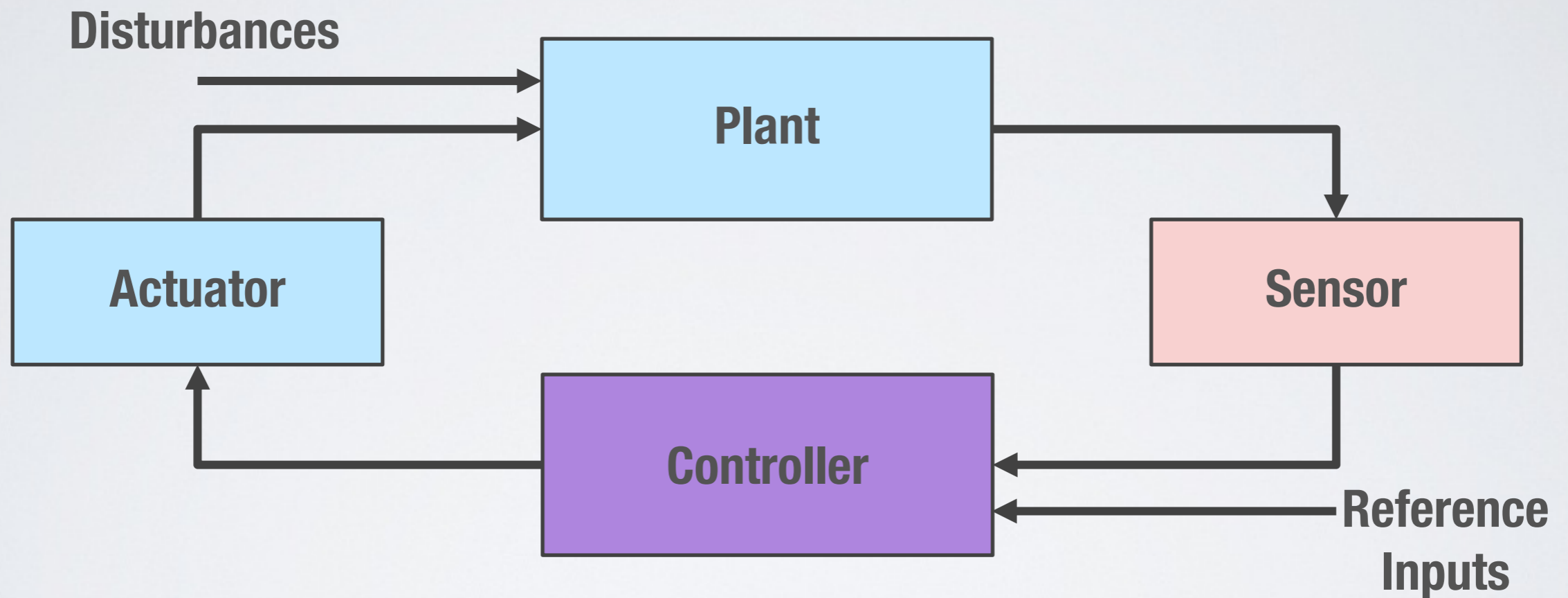
CPS Models

- have **dynamic** behaviors
- are **executable**
- are **hybrid** – capture both discrete (algorithms) and continuous (physical dynamics) computations
- exhibit **uncertainty** e.g., about the environment

Open Loop Controllers

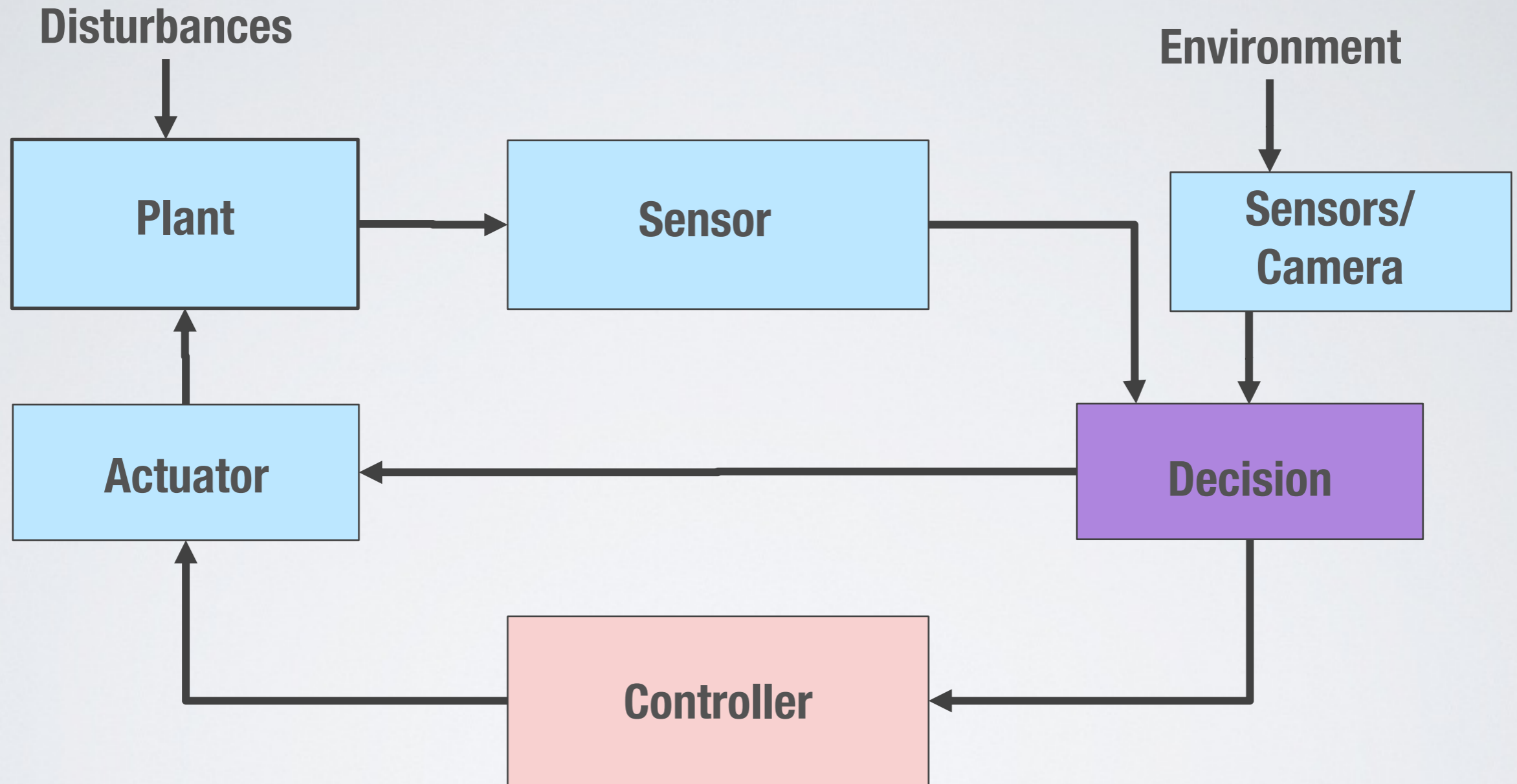


Closed Loop Controllers



Controllers + Plants

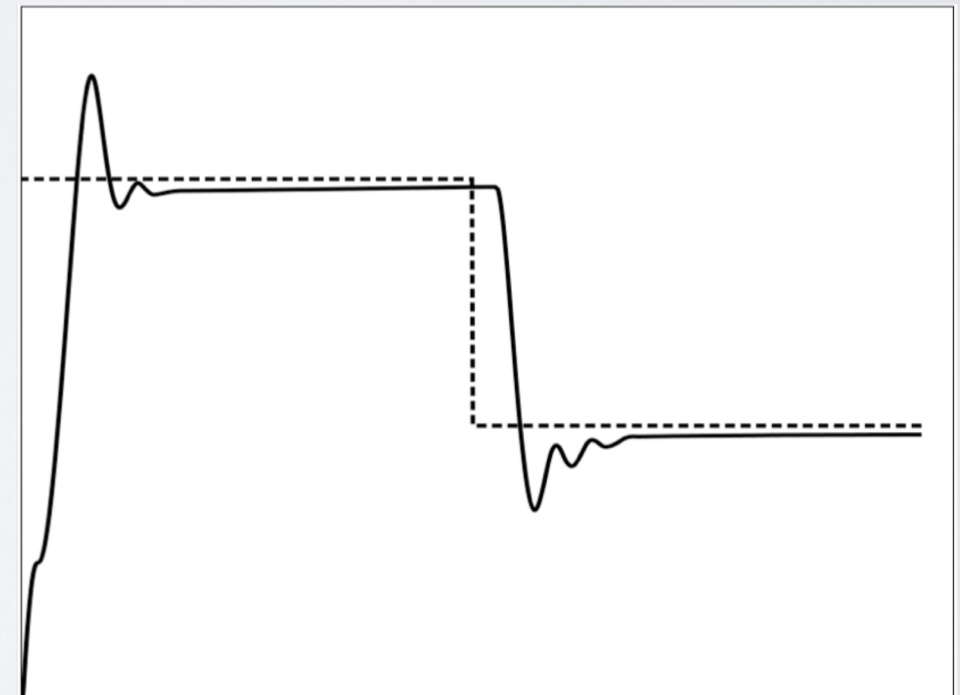
Autonomous Controllers



Controllers + Plants + Decision

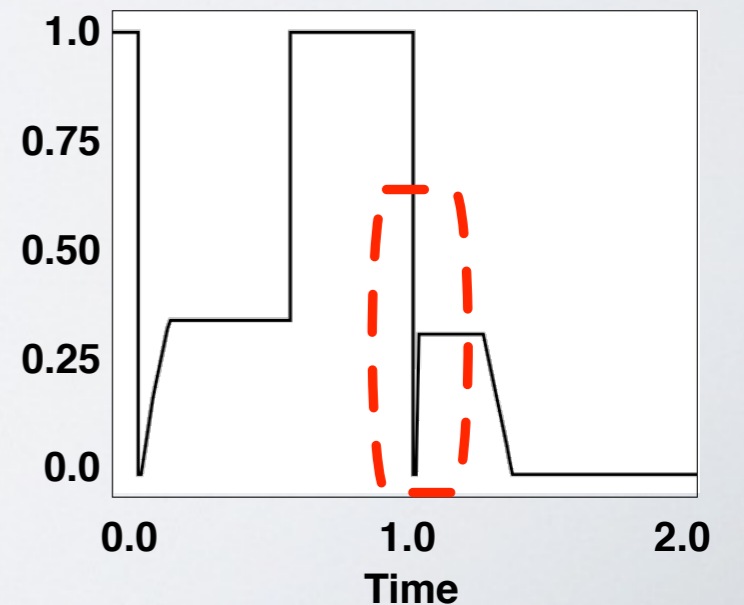
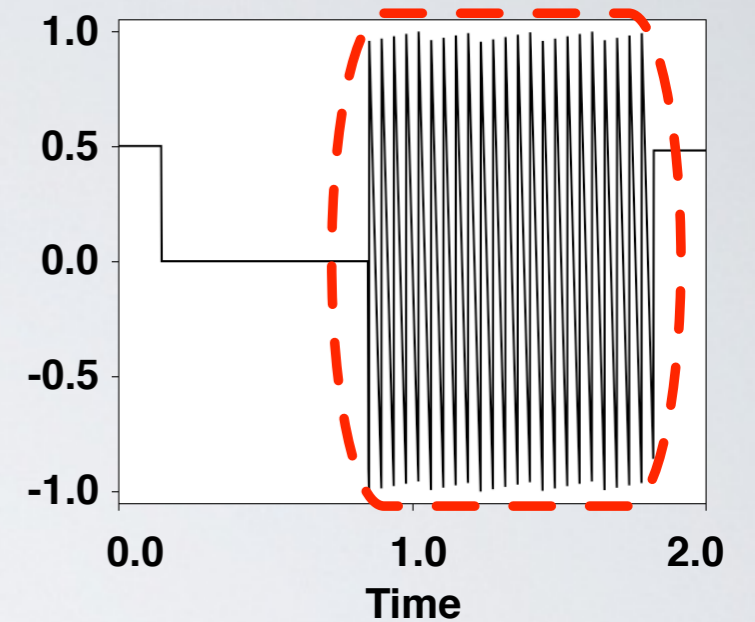
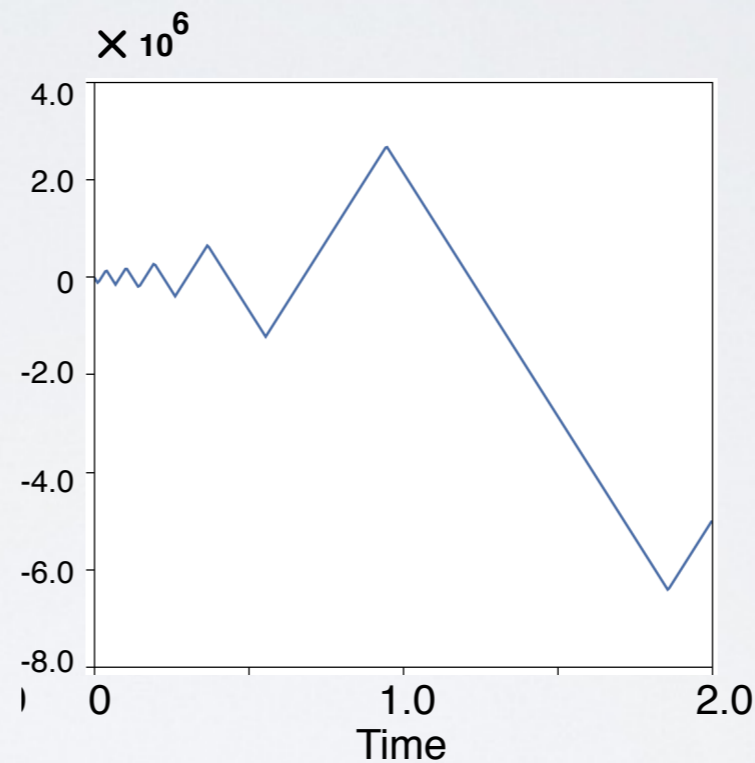
CPS Test Oracles

- System outputs are **signals**
 - Engineers inspect changes in outputs over continuous time periods
- Test oracles
 - may be **heuristic** or **partial**
 - are often **quantitative** and not binary
 - might be **effort-intensive** or difficult to **automate**



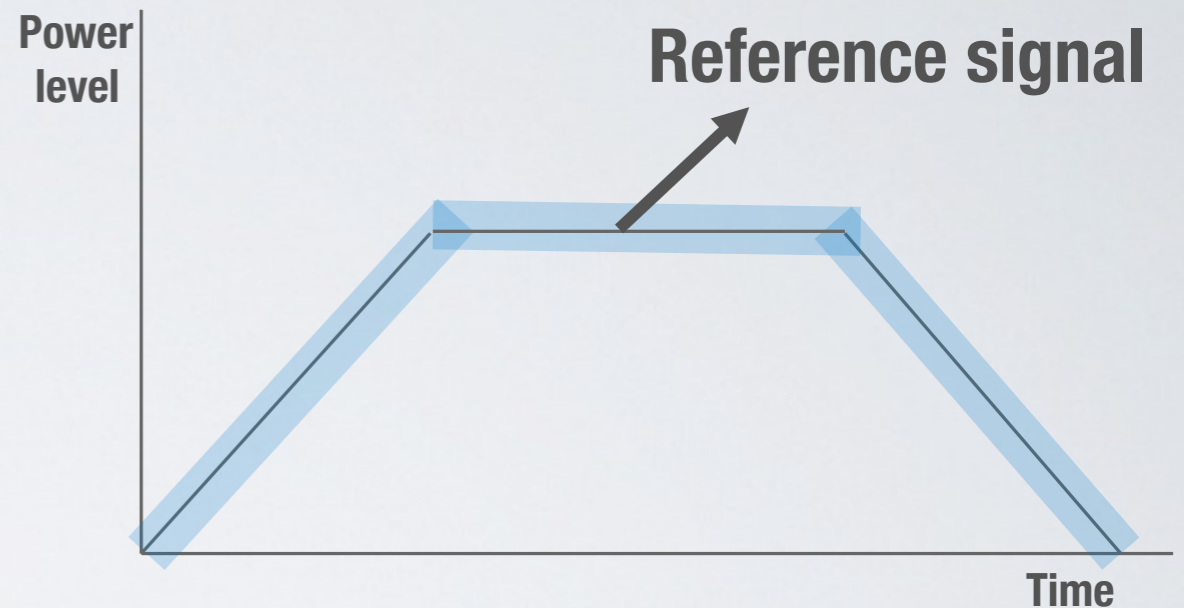
Anti Patterns– Partial Oracles

- **Instability**
- **Growth to infinity**
- **Discontinuity**

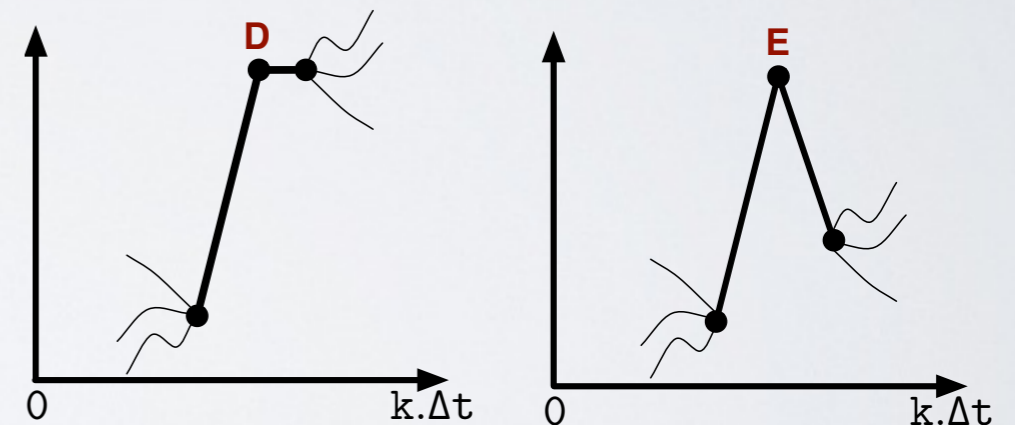


Application Specific Oracles

- A reference signal + error margin



- (Sequences of) Signal features



- Temporal properties: “The system response should occur within 32ms”

CPS Testing Challenges

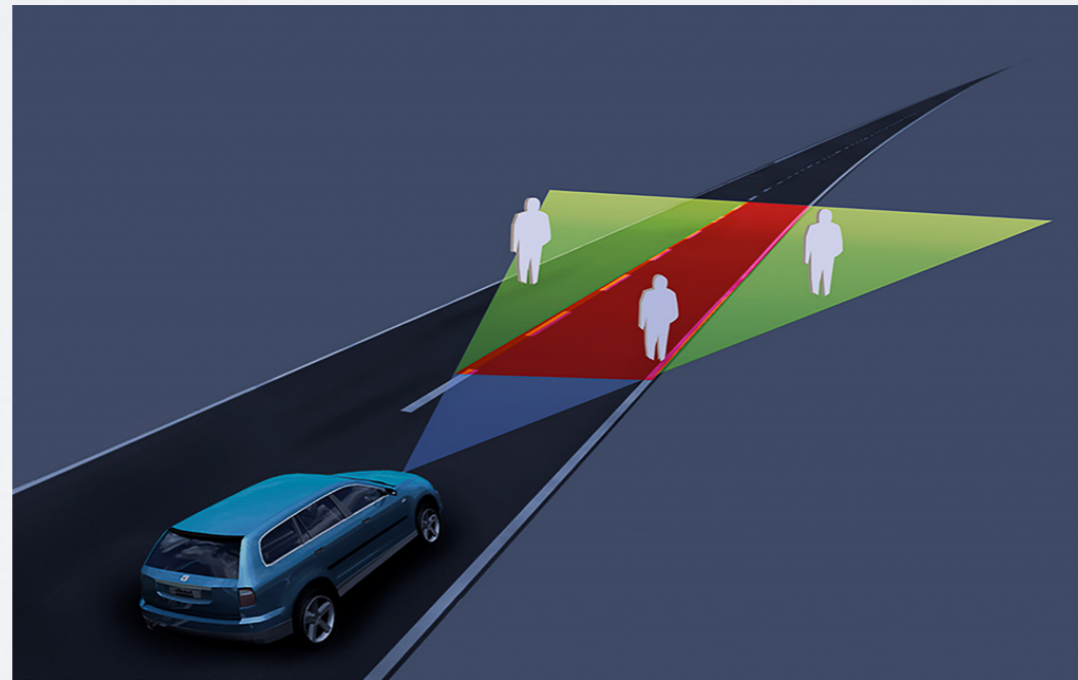
- Test input space is **large** and **multi-dimensional**
- Model executions are **time consuming**
- **Fault localization** is difficult
- **Limited time budget** for testing
 - Test oracles are expensive
 - Running the test cases on HiL is expensive

Our Solutions

Challenges	Our solution
Test input space is large	Metaheuristic search to identify worst case/critical behaviors
Simulation takes time	Surrogate models to predict the simulation outcome without running simulations
Fault localization is difficult	Classification techniques to explain system failures
Expensive HiL Testing	Test case prioritization using multi-objective search

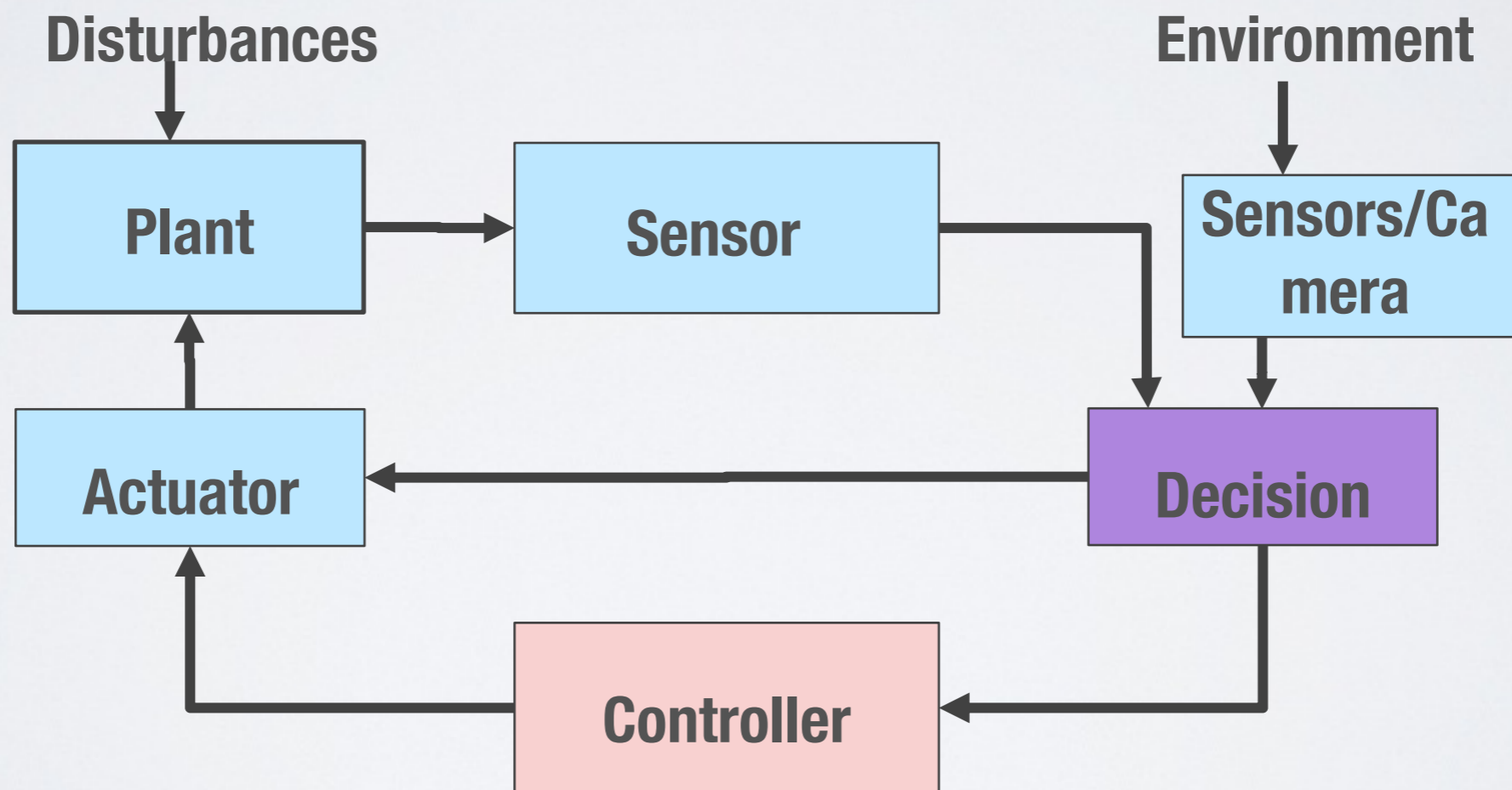
Example Projects

Testing Advanced Driver Assistance Systems



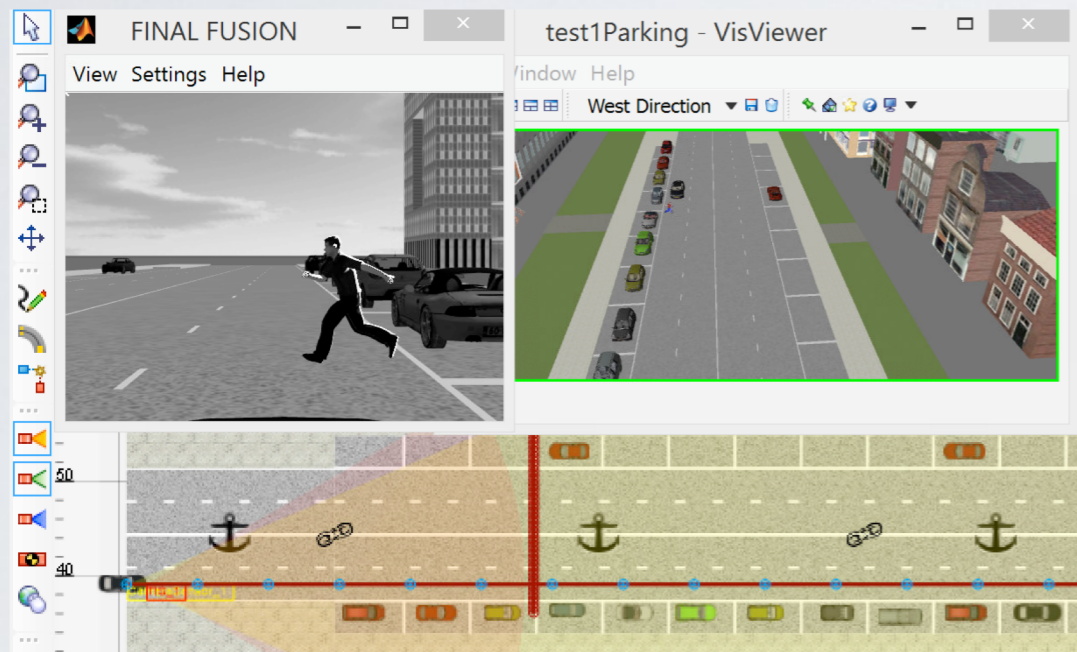
Advanced Driver Assistance Systems (ADAS)

Decisions are made over time based on sensor data



Testing Advanced Driver Assistance Systems (self-driving cars)

Models -- A simulator based on Physical/Mathematical models



Oracles -- description of crashes

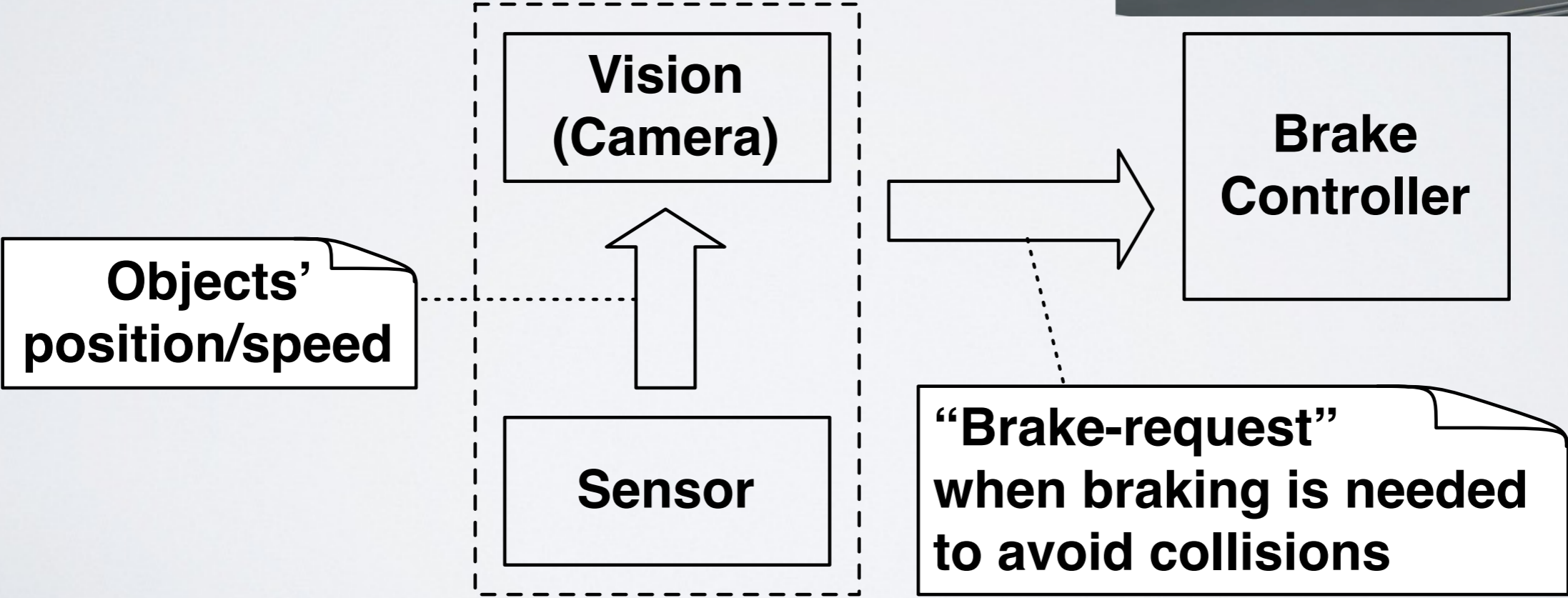


- Test generation based on **meta-heuristic** search
- **Surrogate** modeling to speed up search
- **Classification** to help with fault localization

Automated Emergency Braking System (AEB)



Decision making



Physics-Based Simulations

AEB Critical Behavior -- Oracle

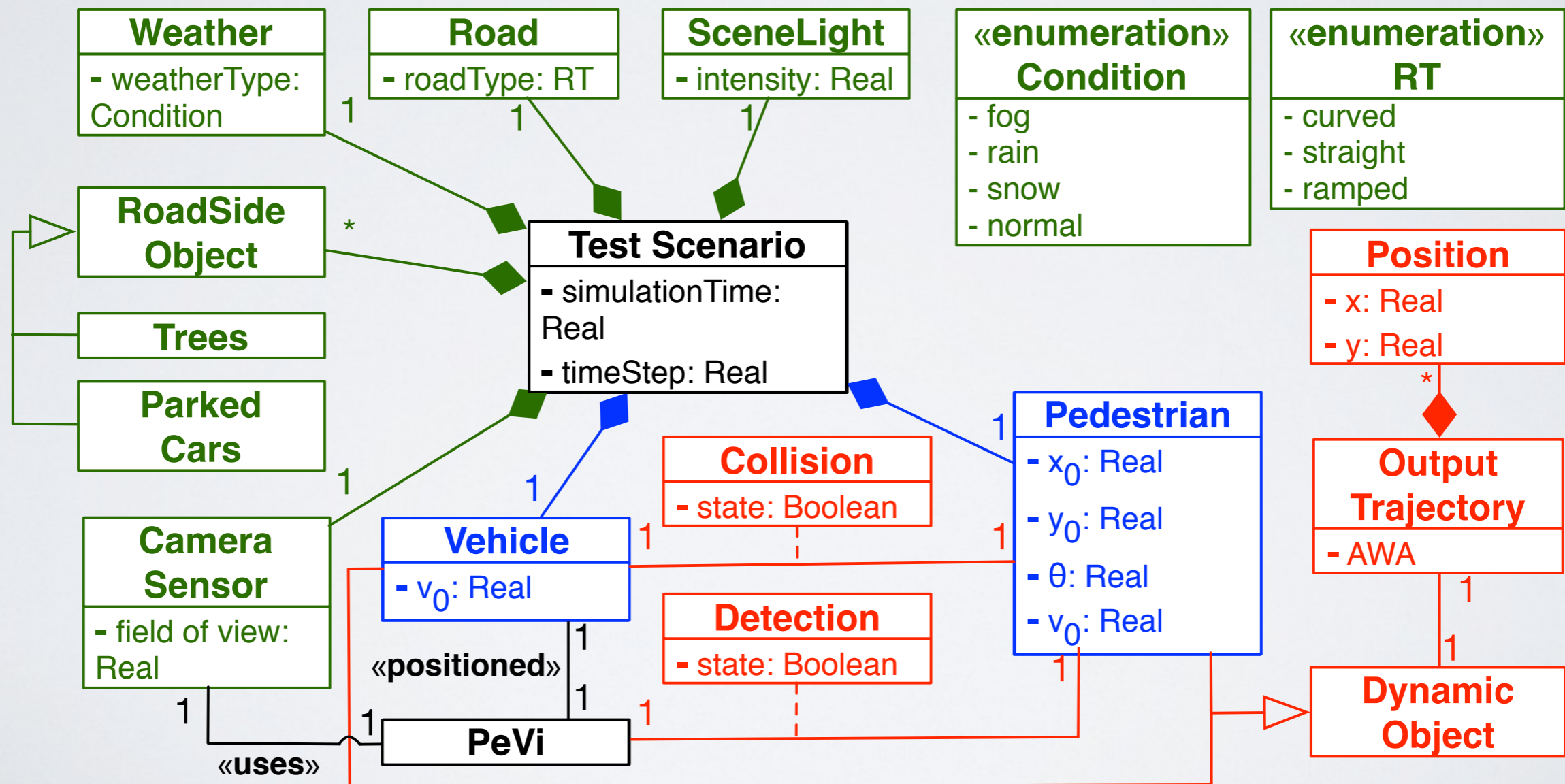
Example:

CB: “AEB detects a pedestrian in front of the car with a high degree of certainty, but an accident happens where the car hits the pedestrian with a relatively high speed”



Input/Output Specification

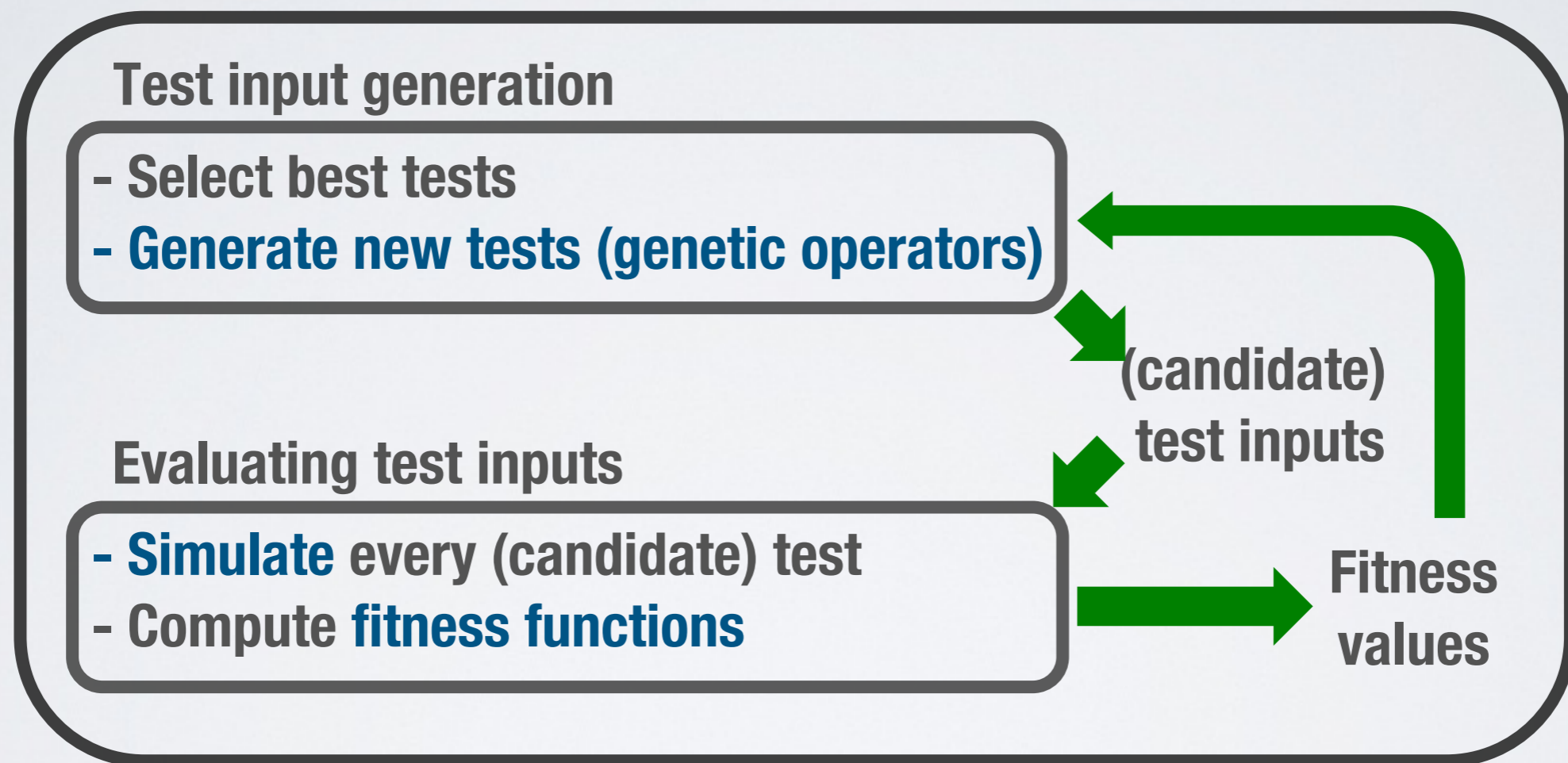
Static inputs
Dynamic inputs
Outputs



Generating Critical Test Scenarios via Metaheuristic Search

Black-Box Search-based Testing

Input data ranges/dependencies + Simulator + Fitness functions defined based on Oracles



Test cases revealing worst case system behaviors

An example critical scenario

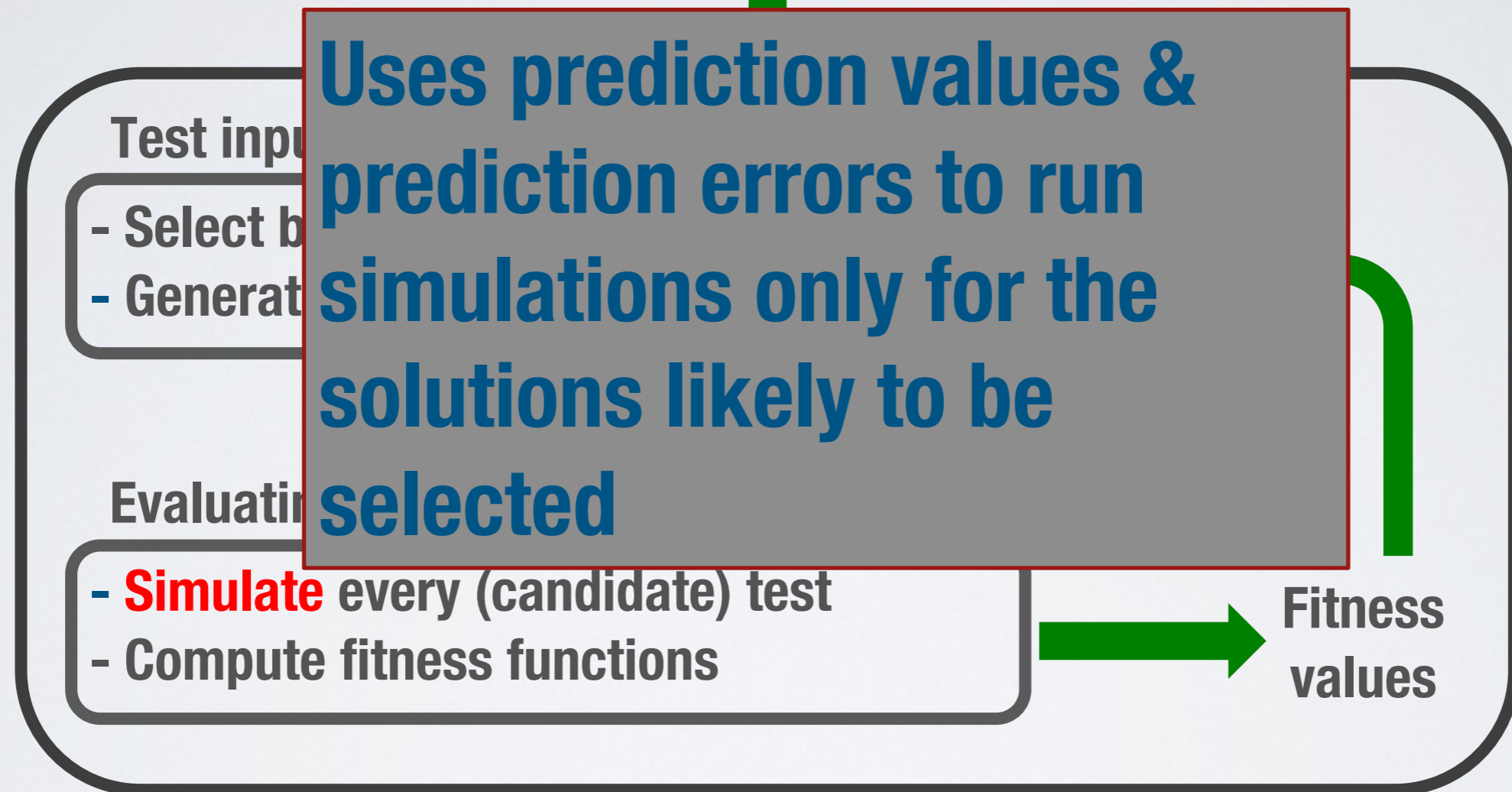
Improving Search Time Performance via Surrogate (Prediction) Models

Improving Time Performance

- Individual simulations take on average around 1min
 - It takes 8 hours to run our search-based test generation (\approx 500 simulations)
- We use **surrogate modeling** to improve the search
- **Goal:** Predict fitness based on dynamic variables
 - Neural networks

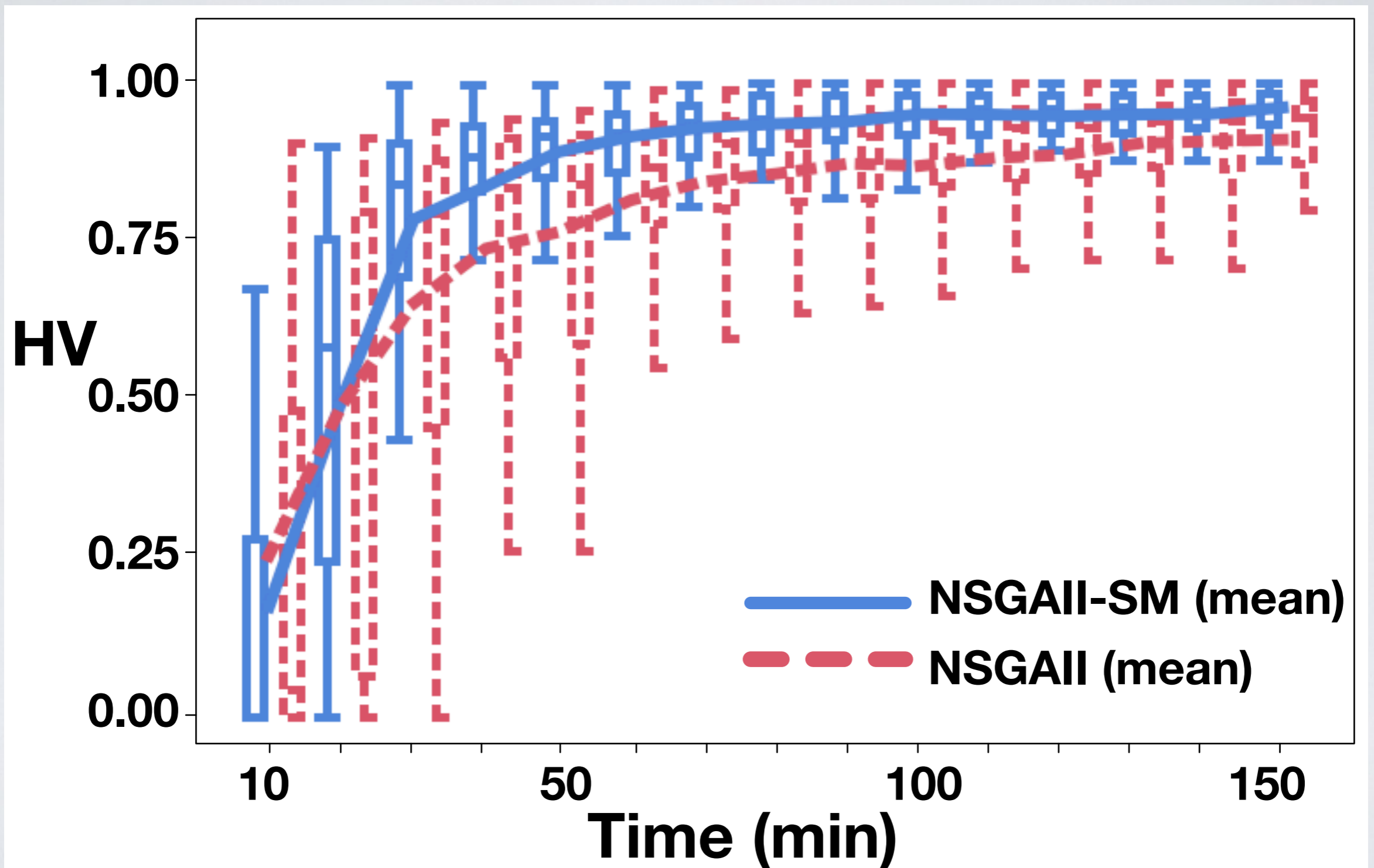
Surrogate Modeling

Input data ranges/dependencies + Simulator + Fitness functions defined based on Oracles



Test cases revealing worst case system behaviors

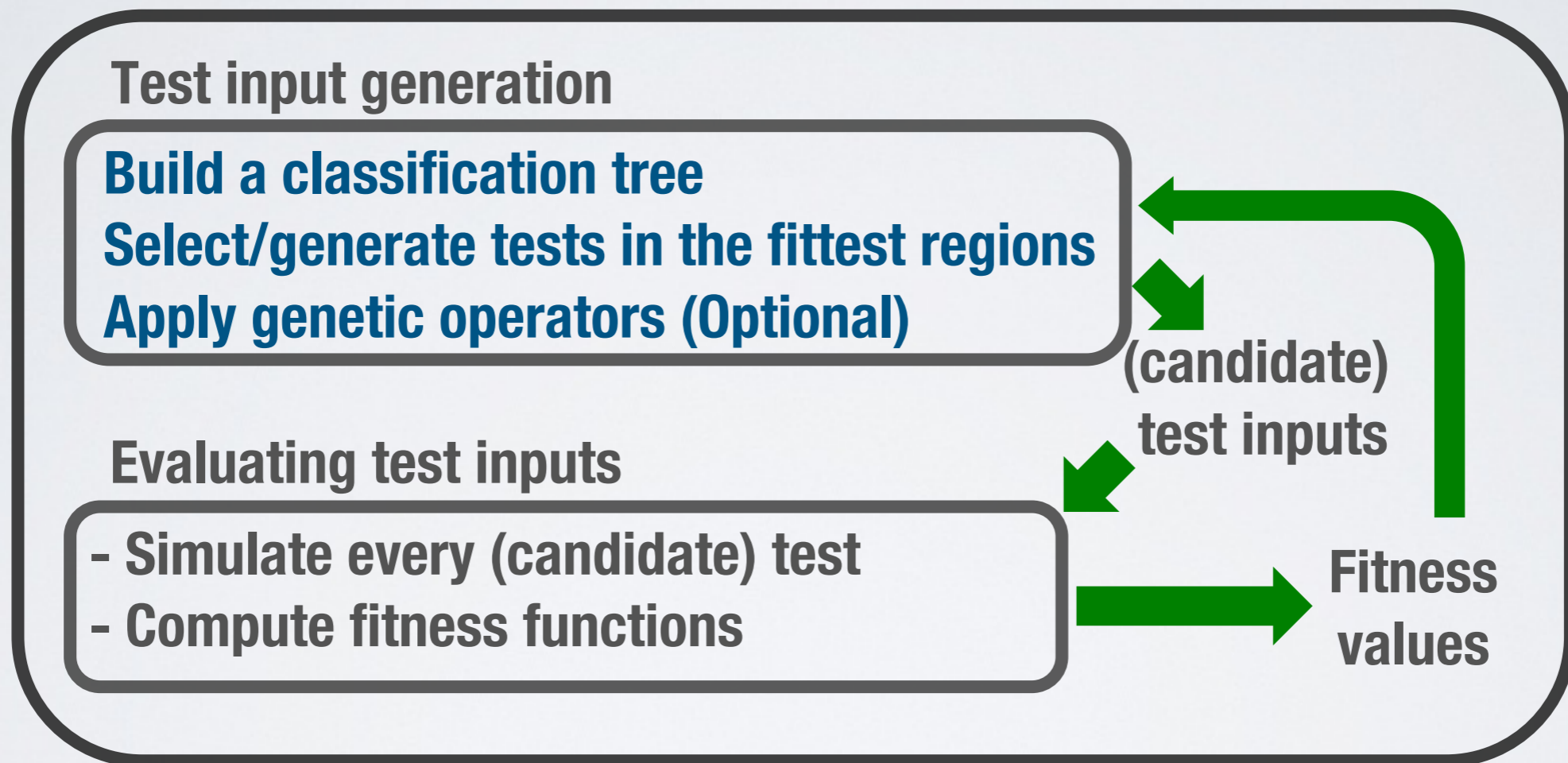
Results – Surrogate Modeling



Guiding Search via Classification Models

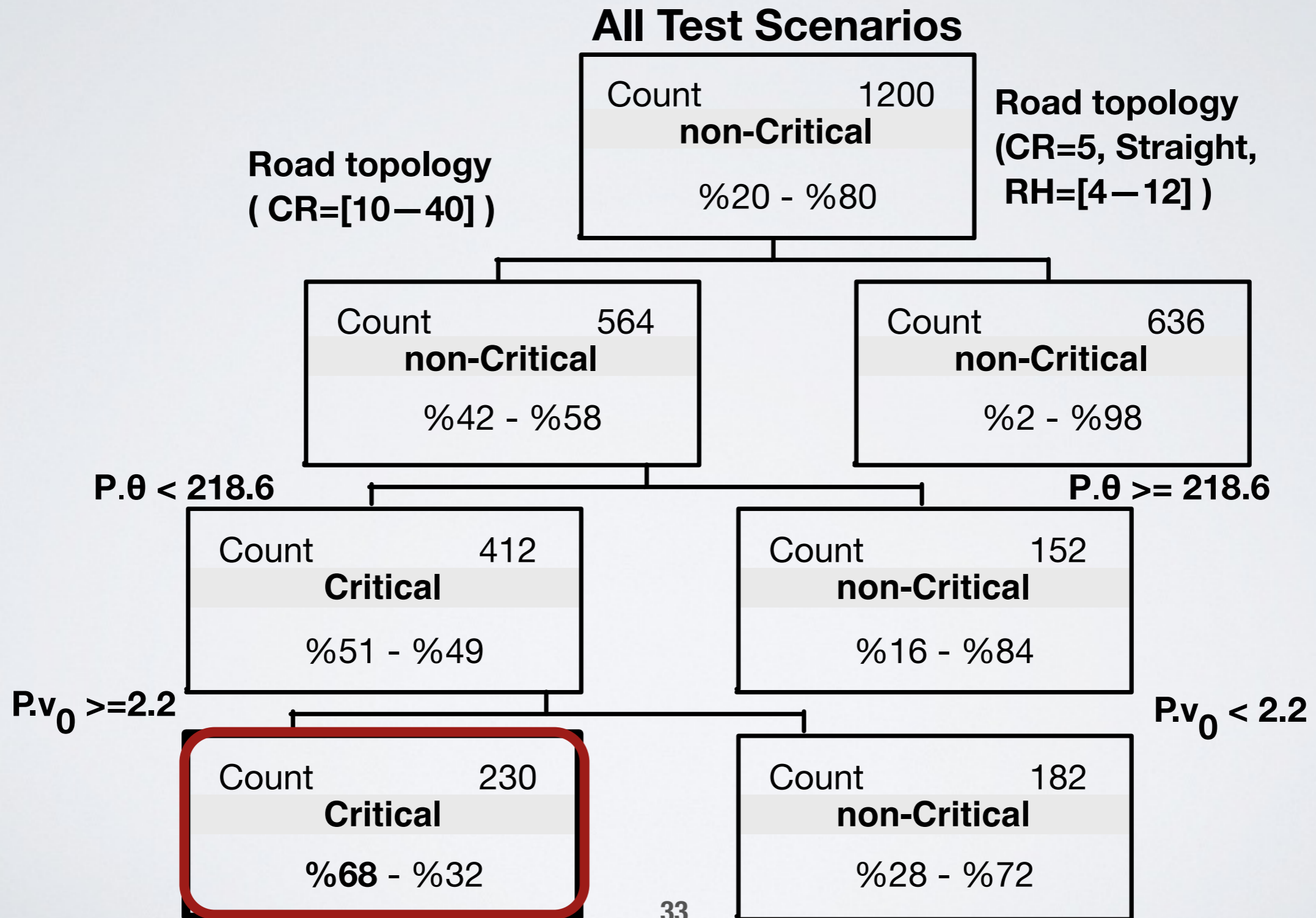
Search Guided by Classification

Input data ranges/dependencies + Simulator + Fitness functions defined based on Oracles

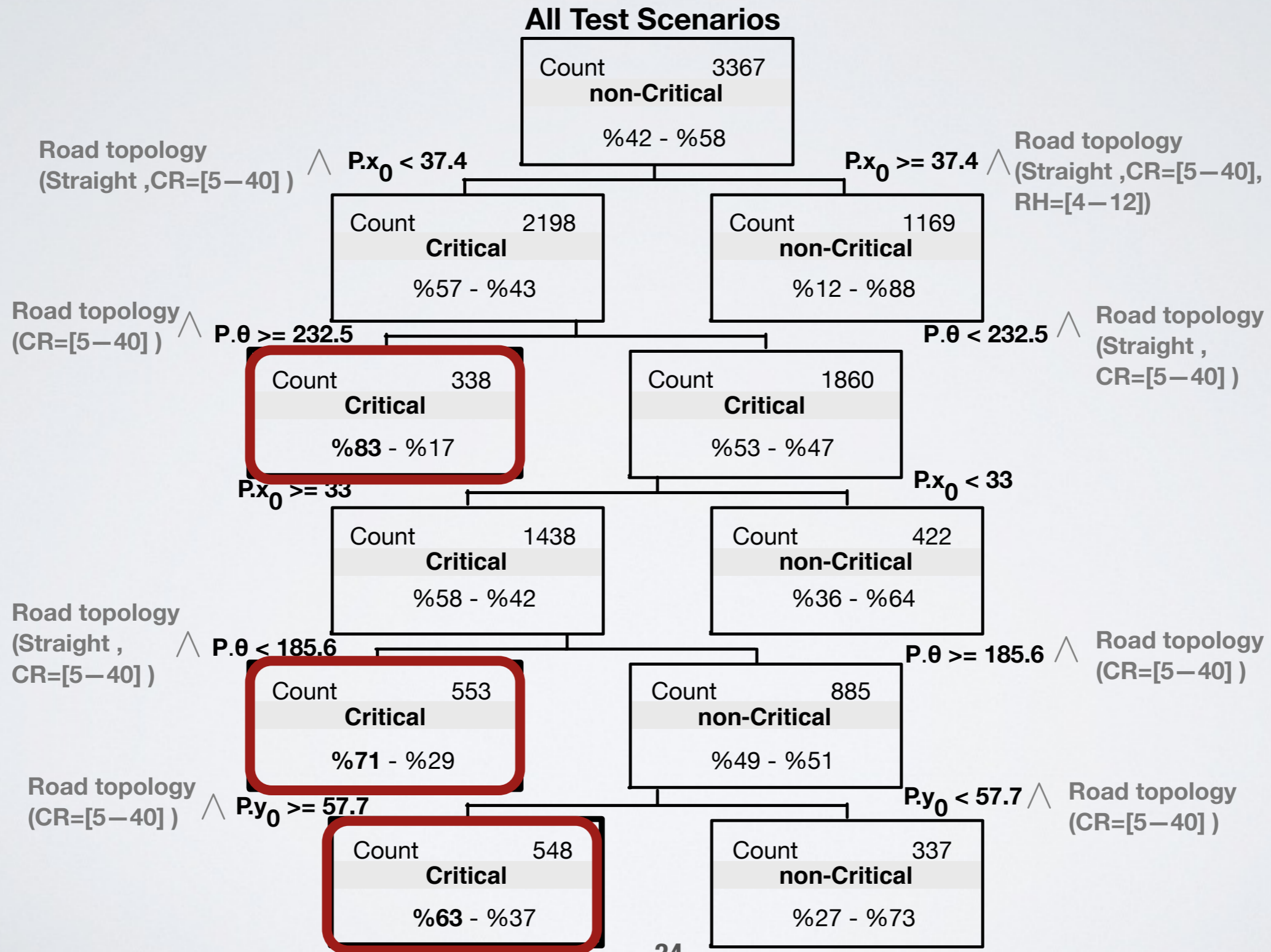


Test cases revealing worst case system behaviors +
A characterization of critical input regions

Initial Classification Model



Refined Classification Model



Outputs of Our Approach

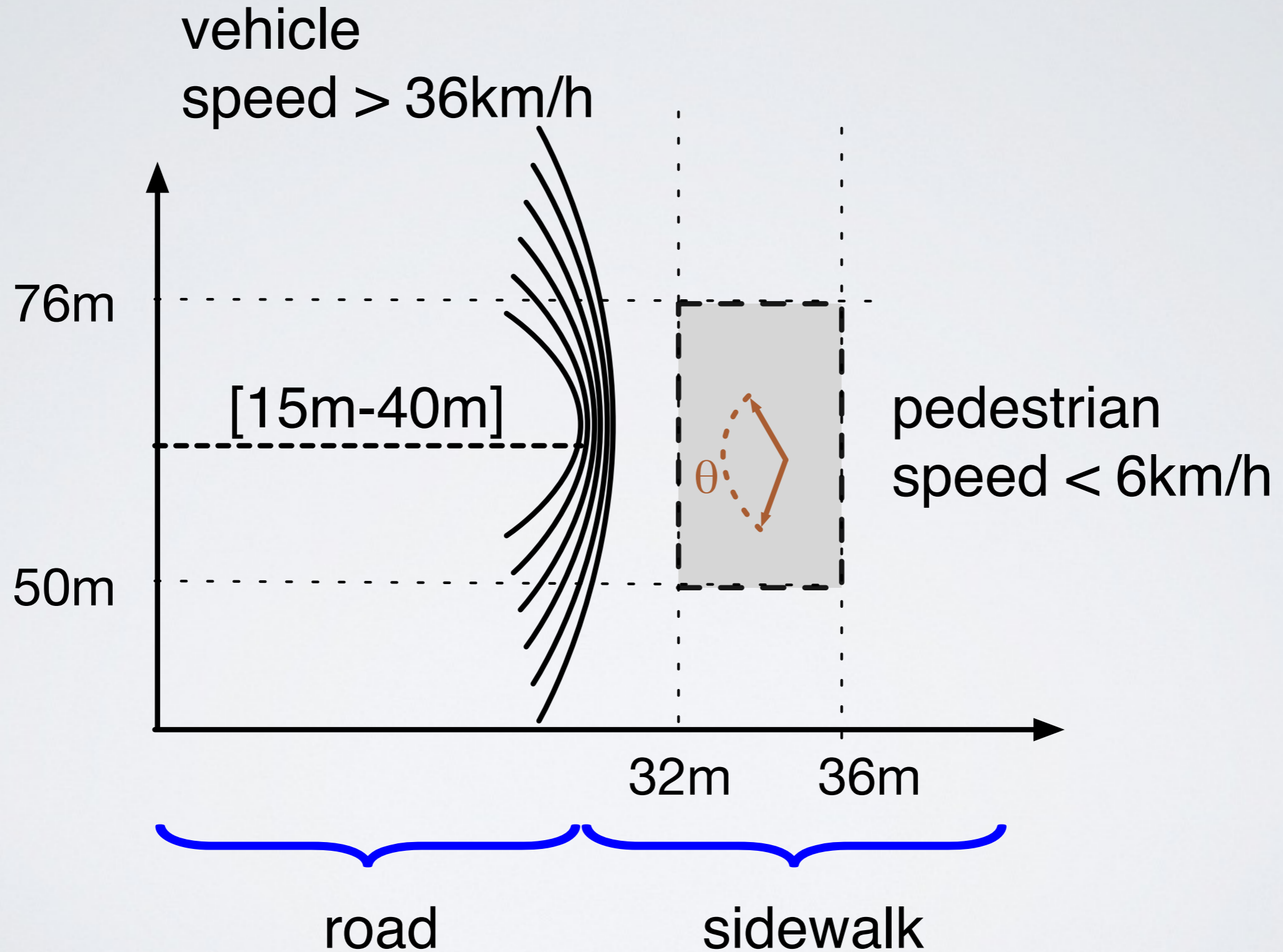
- **Failure Detection**

- (Search + Classification) generates 78% more **distinct, critical test scenarios** compared to a baseline search algorithm

- **Failure Explanation**

- A characterization of the input space showing under what input conditions the system is likely to fail
- Visualized by diagrams or regression trees

Failure Explanation



Usefulness

The characterizations of the different critical regions can help with:

- (1) **Debugging** the system or the simulator
- (2) **Identifying hardware changes** to increase ADAS safety
- (3) **Identifying proper warnings** to drivers

Other Project Examples

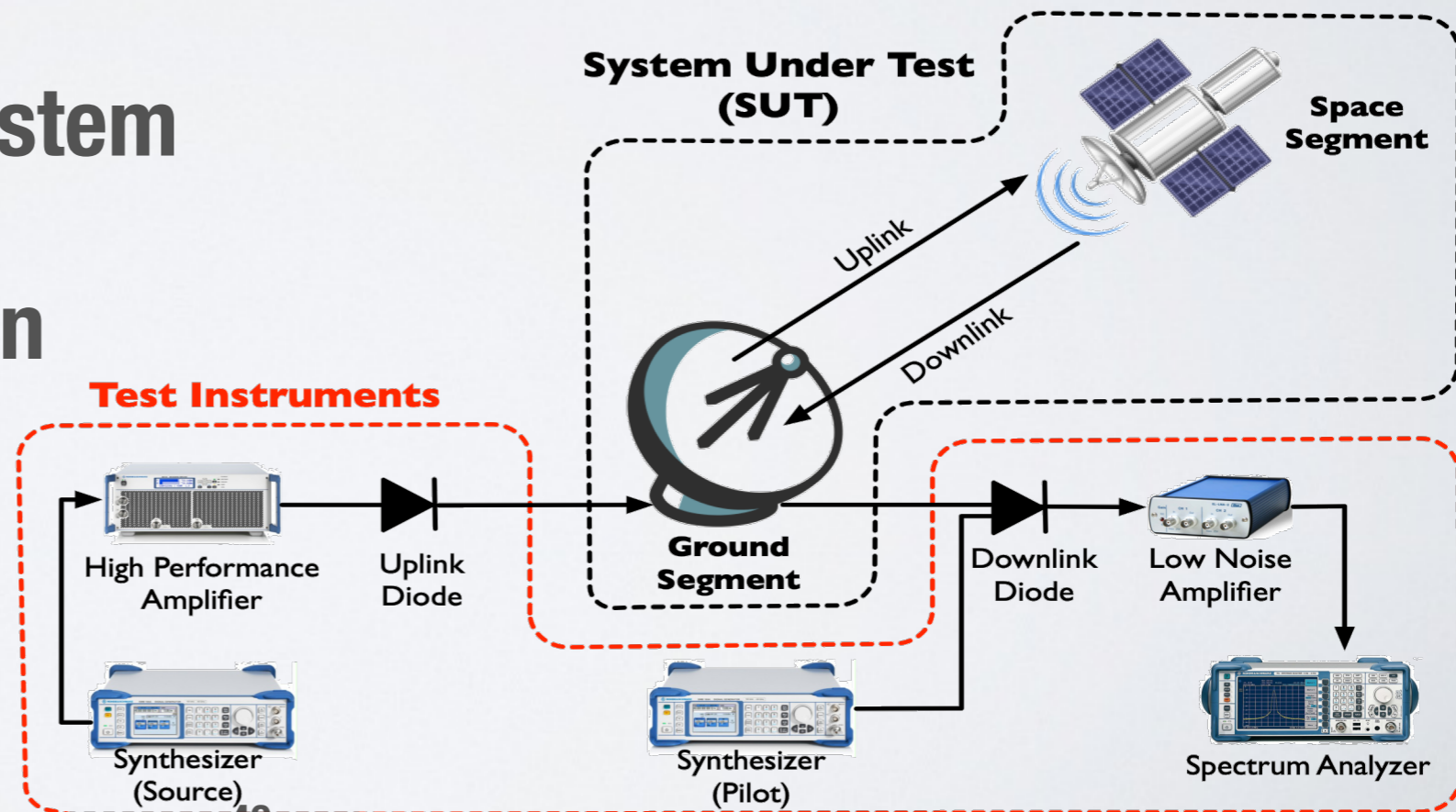
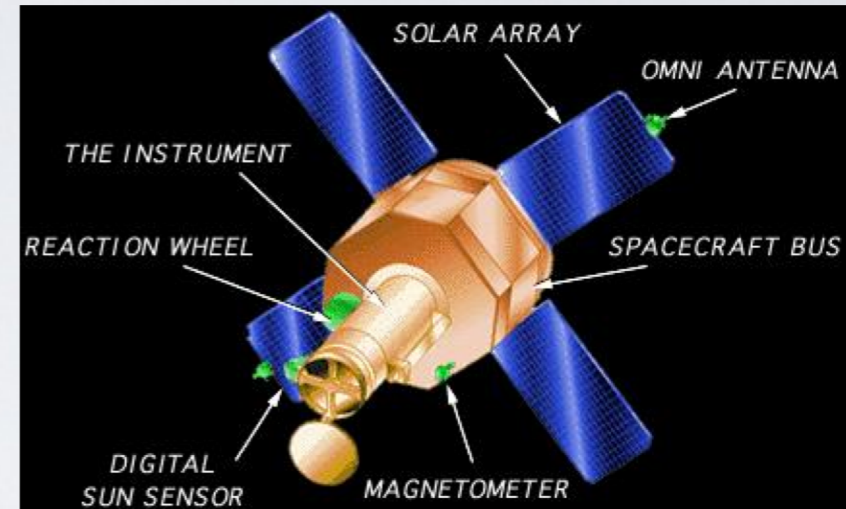
Automotive Systems

- **Testing controller implemented in Simulink**
- **Analysis of CPU time usage in ECU software**
- **Fault localisation in Simulink models**



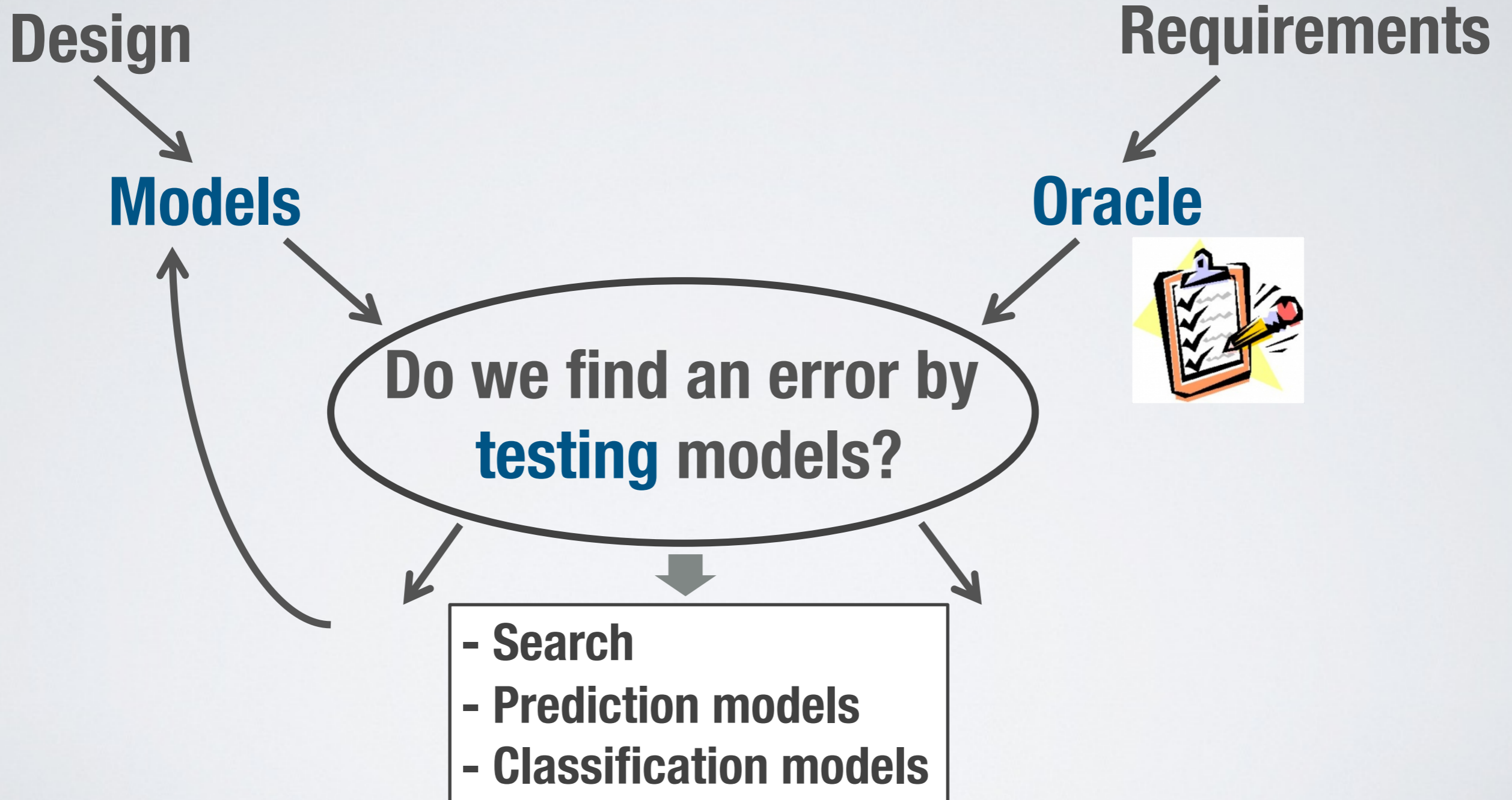
Model Testing Satellite Systems

- Control system
 - MiL/SiL testing
- Data communication system
 - Test case prioritization for HiL

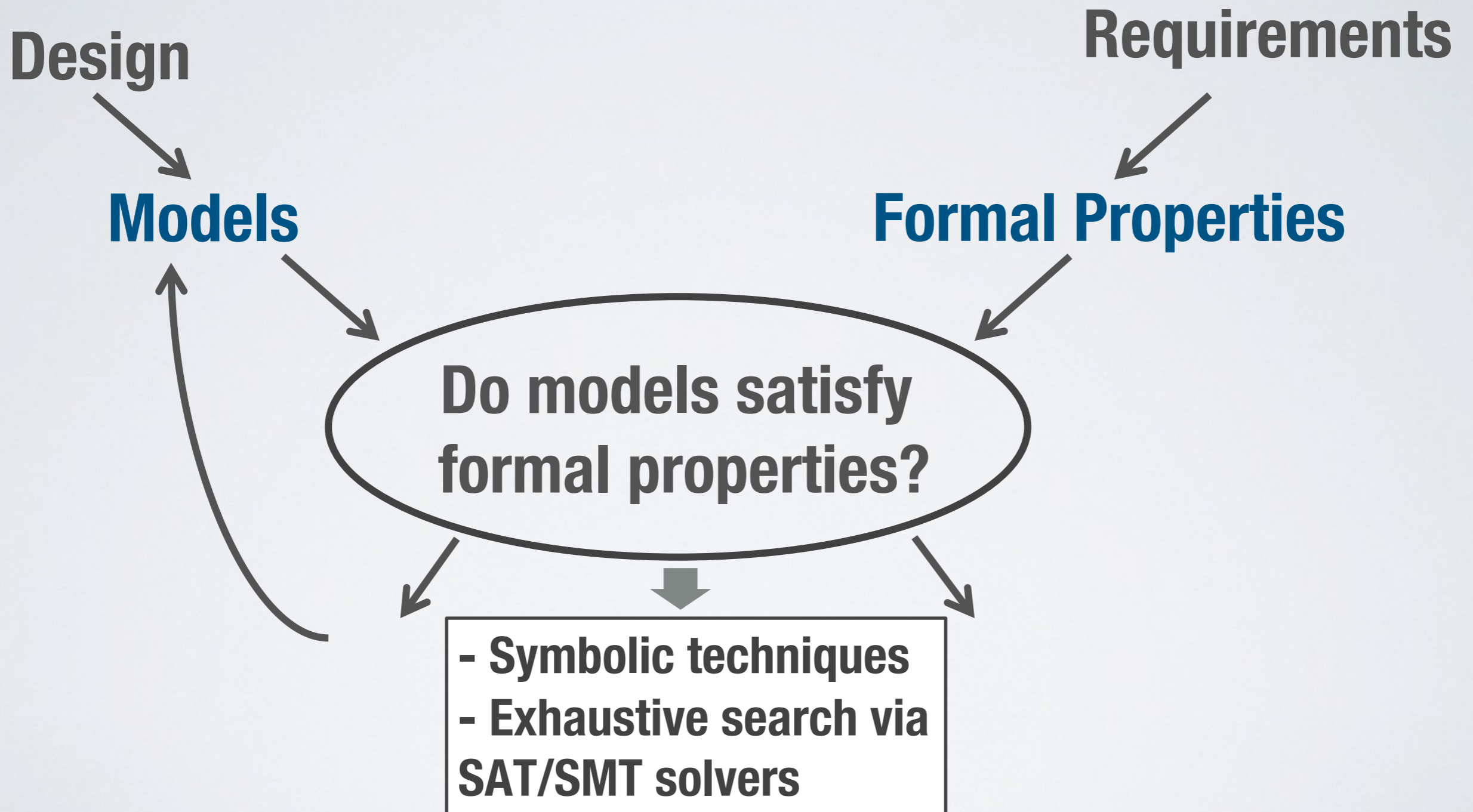


Conclusions

Model Testing



Model **Checking**



Related Work: Model Checking

- **Incompatibility** issues with CPS models
 - **Continuous mathematical models**, e.g., differential equations
 - Library functions in **binary code**
 - **Non-linear** behavior
 - **Complex mathematical operators**
 - **Saturation** of actuators and sensors
 - Reliance on **measured data**

Related Work: Model Checking

- **Unrealistic assumptions** about CPS test oracles
 - Discrete/exact/complete/binary/automatable
 - Focus on structural coverage
- **Scalability**

Search-Based Solutions

- Are Versatile
 - Decrease **modeling** requirements
 - Relax assumptions on **test oracles**
- Are scalable, e.g., **easy to parallelize**
- Can be combined with: **Machine learning; Statistics; Solvers, e.g., SMT, CP**
- But,
 - are **context-dependent**
 - require **massive empirical studies**

Future Work

- **Model testing solutions in other CPS contexts**
 - **Heterogeneous modeling and co-simulation**
 - **Modeling dynamic properties and risk**
 - **Uncertainty modeling enabling probabilistic test oracles**
 - **Executable model at a proper level of precision for testing purposes**
 - **Systematic ways to build fitness functions for oracles**

References

- **Raja Ben Abdessalem, Shiva Nejati, Lionel C. Briand, Thomas Stifter, “Testing Vision-Based Control Systems Using Learnable Evolutionary Algorithms”, To appear in ICSE 2018**
- **Raja Ben Abdessalem, Shiva Nejati, Lionel C. Briand, Thomas Stifter, “Testing Advanced Driver Assistance Systems Using Multi-Objective Search and Neural Networks”, ASE 2016**
- **Reza Matinnejad, Shiva Nejati, Lionel C. Briand, Thomas Bruckmann, “Automated Test Suite Generation for Time-continuous Simulink Models”, ICSE 2016**
- **Reza Matinnejad, Shiva Nejati, Lionel C. Briand, Thomas Bruckmann, “Effective Test Suites for Mixed Discrete-Continuous Stateflow Controllers”, ACM ESEC/FSE 2015 (Distinguished paper award)**
- **Reza Matinnejad, Shiva Nejati, Lionel C. Briand, Thomas Bruckmann, “MiL Testing of Highly Configurable Continuous Controllers: Scalable Search Using Surrogate Models”, IEEE/ACM ASE 2014 (Distinguished paper award)**
- **Reza Matinnejad, Shiva Nejati, Lionel C. Briand, Thomas Bruckmann, Claude Poull, “Search-Based Automated Testing of Continuous Controllers: Framework, Tool Support, and Case Studies”, Information and Software Technology, Elsevier (2014)**

Automated Testing of Cyber-Physical Systems

Shiva Nejati

SnT Centre/University of Luxembourg

Huawei Workshop on Applications of AI to
Software Engineering

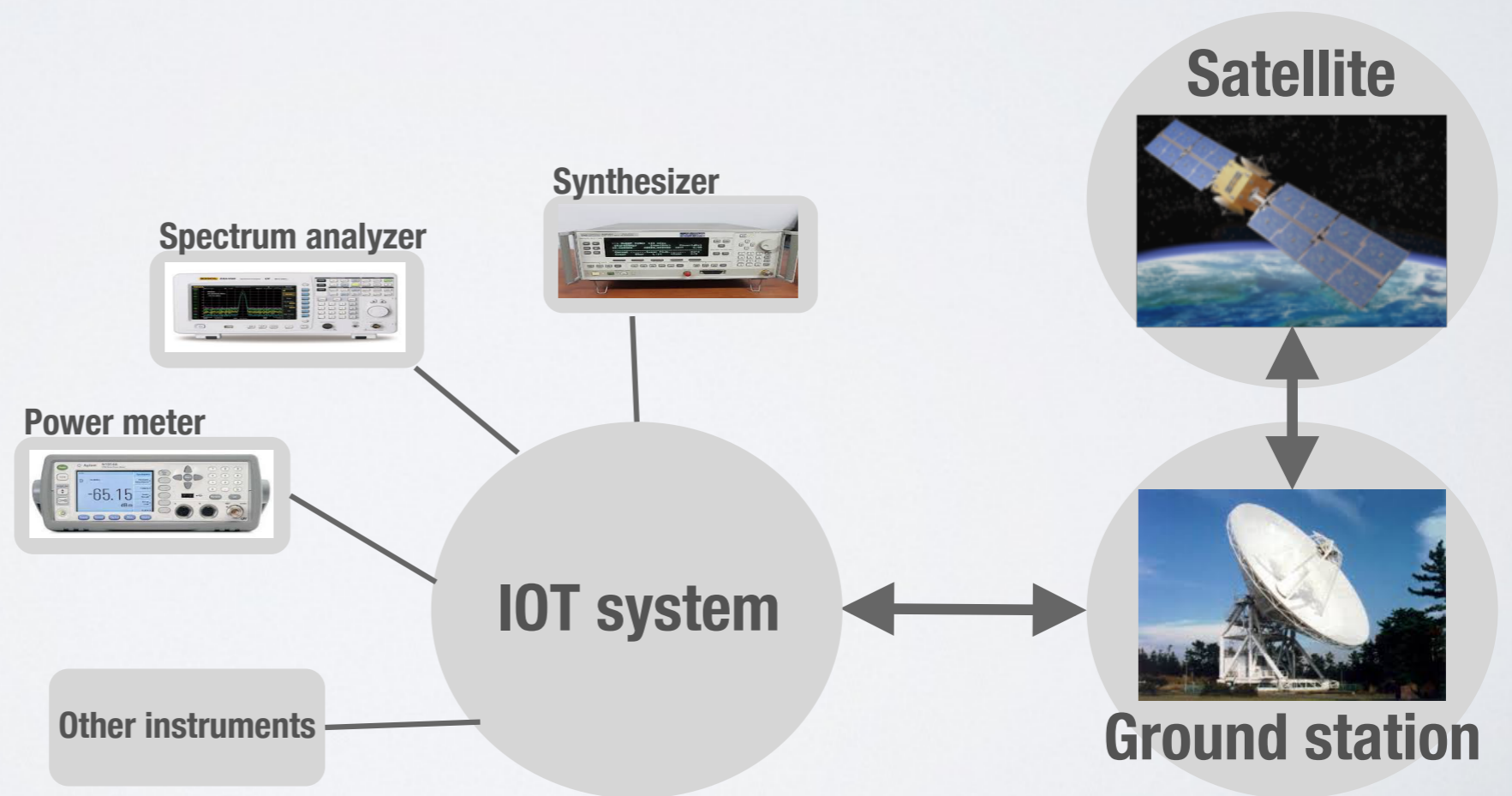
December 15, 2017

Results

- The test scenarios by our search-based approach helped engineers **identify** several **critical behaviors**
 - The critical test scenarios are available at:

<https://sites.google.com/site/testingpevi>
- Under tight time budget, our search algorithm with surrogate models is more **accurate** and **safer** compared to the baseline search algorithm
- Our classification guided search generates 78% more **distinct, critical test scenarios** compared to the baseline search algorithm

Part II. Model Testing Satellite Systems



Test Case Prioritization (HiL)

- **Problem**

- **Test case prioritization**



Search space: **exponential** growth

E.g., two test cases: a, b

Possible test suites: (a), (b), (a,b), (b,a)

- **Context**

- **System validation and acceptance testing of CPS**



Black box testing

Results – Worst Runs

